**Date Submitted: 11/10/19**

**------------------------------------------------------------------------------------**

**Task 01:**

Youtube Link: <https://youtu.be/hnmQxZ1FLU0>

Sample output:

A picture containing text

Description automatically generated

Stack space:

A screenshot of a social media post

Description automatically generated

A screenshot of a cell phone

Description automatically generated

Log variables using ROV:

A screenshot of a cell phone

Description automatically generated

**Modified Code:**

/\* For usleep() \*/

**#include** <unistd.h>

**#include** <stdint.h>

**#include** <stddef.h>

/\* Driver Header files \*/

**#include** <ti/drivers/GPIO.h>

// #include <ti/drivers/I2C.h>

// #include <ti/drivers/SPI.h>

// #include <ti/drivers/UART.h>

// #include <ti/drivers/Watchdog.h>

**#include** <ti/drivers/ADC.h>

**#include** <ti/display/Display.h>

/\* Board Header file \*/

**#include** "Board.h"

// Global Variables

uint16\_t adcValue = 0;

uint16\_t threshold = 100;

uint16\_t trigger = 0;

**void** **gpioButtonFxn0**(uint\_least8\_t index)

{

/\* Clear the GPIO interrupt and decrement threshold \*/

**if**(threshold < 250){ // Ensure threshold doesn't go below zero

threshold = 0;

} **else** {

threshold -= 250; // decrement by 250

}

}

**void** **gpioButtonFxn1**(uint\_least8\_t index)

{

/\* Clear the GPIO interrupt and increment threshold \*/

**if**(threshold > 4096){ // Ensure threshold doesn't go above max ADC range

threshold = 4096;

} **else** {

threshold += 250; // increment by 250

}

}

/\*

\* ======== mainThread ========

\*/

**void** \***mainThread**(**void** \*arg0)

{

/\* 1 second delay \*/

uint32\_t time = 100000;

/\* Call driver init functions \*/

**GPIO\_init**();

**ADC\_init**();

// I2C\_init();

// SPI\_init();

// UART\_init();

// Watchdog\_init();

/\* Configure the LED pin \*/

**GPIO\_setConfig**(Board\_GPIO\_LED0, GPIO\_CFG\_OUT\_STD | GPIO\_CFG\_OUT\_LOW);

**GPIO\_setConfig**(Board\_GPIO\_BUTTON0, GPIO\_CFG\_IN\_PU | GPIO\_CFG\_IN\_INT\_FALLING);

**GPIO\_setConfig**(Board\_GPIO\_BUTTON1, GPIO\_CFG\_IN\_PU | GPIO\_CFG\_IN\_INT\_FALLING);

/\* Turn on user LED \*/

**GPIO\_write**(Board\_GPIO\_LED0, Board\_GPIO\_LED\_ON);

// ADC

ADC\_Handle adc;

ADC\_Params params;

**ADC\_Params\_init**(&params);

adc = **ADC\_open**(Board\_ADC0, &params);

**if** (adc == NULL) {

// ADC\_open() failed

**while** (1);

}

// UART

Display\_Handle displayHandle;

Display\_Params displayParams;

Display\_Params\_init(&displayParams);

displayHandle = Display\_open(Display\_Type\_UART, NULL);

/\* install Button callback \*/

**GPIO\_setCallback**(Board\_GPIO\_BUTTON0, gpioButtonFxn0);

**GPIO\_setCallback**(Board\_GPIO\_BUTTON1, gpioButtonFxn1);

/\* Enable interrupts \*/

**GPIO\_enableInt**(Board\_GPIO\_BUTTON0);

**GPIO\_enableInt**(Board\_GPIO\_BUTTON1);

**while** (1) {

int\_fast16\_t res;

res = **ADC\_convert**(adc, &adcValue);

Display\_printf(displayHandle, 1, 0, "ADC Reading %d", adcValue);

Display\_printf(displayHandle, 1, 0, "Threshold %d", threshold);

**if** (res == ADC\_STATUS\_SUCCESS) {

**if**(adcValue >= threshold){ // arbitrary threshold

**GPIO\_write**(Board\_GPIO\_LED0, Board\_GPIO\_LED\_ON);

trigger = 1;

} **else**{

**GPIO\_write**(Board\_GPIO\_LED0, Board\_GPIO\_LED\_OFF);

trigger = 0;

}

}

**usleep**(time);

}

}

**------------------------------------------------------------------------------------**

**Task 02:**

Youtube Link: https://youtu.be/3F80qL9KU4Y

**Code is unchanged.**

